

Teaching Control Engineering Courses: Is integrating theory & practice a recipe for success?

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Contents

- The story
- EnDiF courses
- Control topics in Engineering programs
- Combining theory concepts with practice
- Engaging students: learning by doing
- Bridging theory & practice: tools & examples
- Is a recipe for success?
- Final remarks

The Engineering Institute



The Engineering Institute

- Our story: from the Institute to Department
- 1990: the Faculty of Engineering
- 2012: the Department of Engineering
- Courses organisation
 - – 1992: academic year of 8 months
 - 1993: 2 semesters
 - 2000 – 2004: from bimester to trimesters
 - 2005 – : 2 periods of 4 months per year

Engineering Dept: EnDiF



Engineering Dept: EnDiF

- ❑ – 2000: from 5 years degree to 3 + 2
- ❑ Bachelor and Master programs: 3 + 2
 - 4 groups: Computer Science, Electronics, Telecommunications and Automatic Control
- ❑ 1 common Bachelor degree in Electronics & Computer Science (2012, former 'Information Science')
- ❑ 2 Master degrees in Automatic Control & Computer Sciences, Electronics & Telecommunications

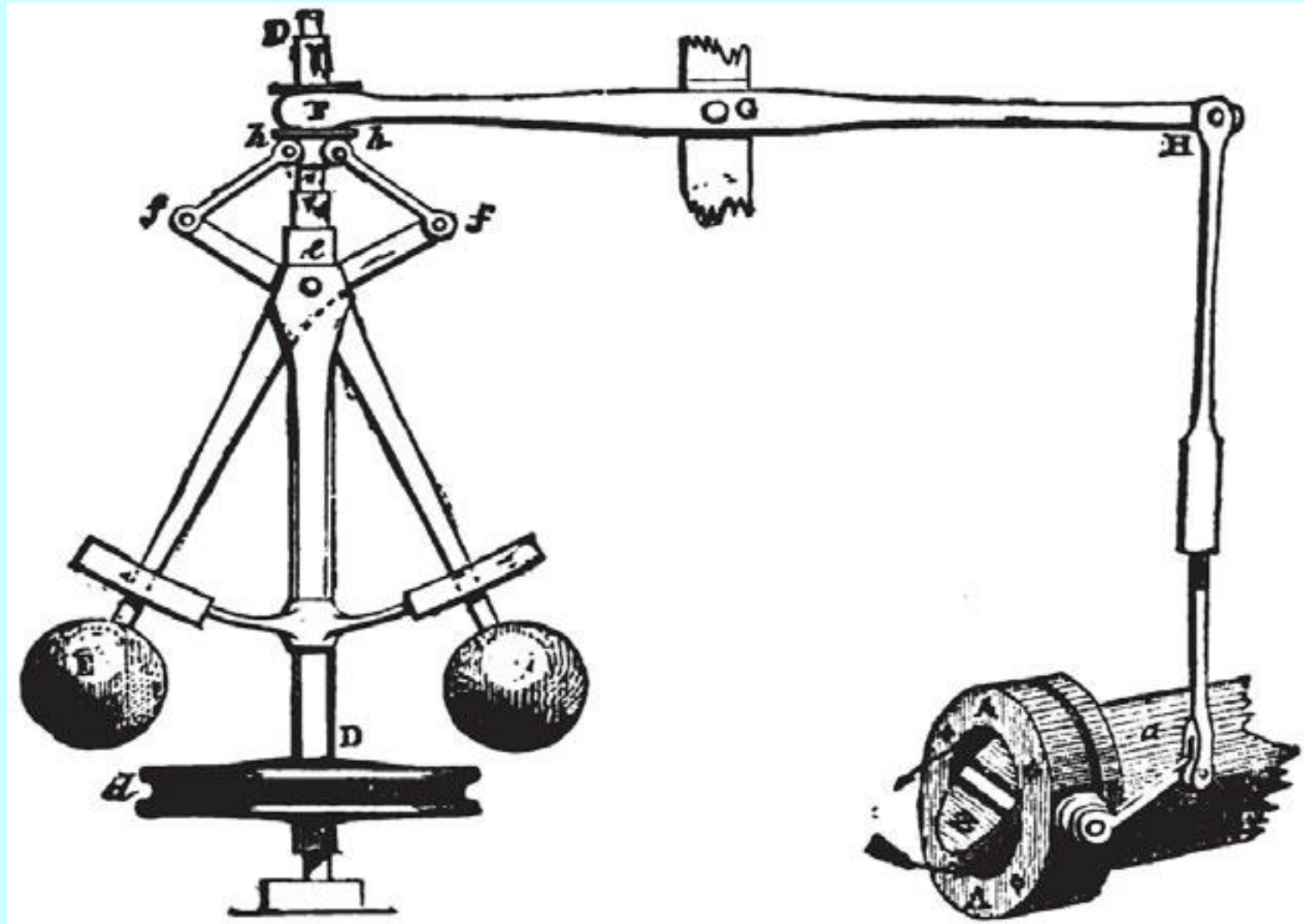
Current Organisation



Engineering Curriculum

- Bachelor program:
 - 1st year: Mathematics, Physics & Computer Science basic courses
 - 2nd year: Mathematics, Physics & Computer Science basic courses + curricula courses
 - 3rd year: curricula courses (Elect. or Comp. Sc.)
- Master program:
 - 1st year: basic + elective courses
 - 2nd year: elective courses

Control Topics in BSc & MSc



Control Topics in BSc & MSc

- ✓ Bachelor program:
 - 2nd year: Automatic Control (II semester)
 - 3rd year: Digital Control Systems + System Identification (II semester)
- ✓ Master program:
 - 1st or 2nd year: Advanced Control Techniques + Fault Diagnosis (I semester)
- 2002 – : reduction in teachers' hours
- Laboratory facilities & tools
- Courses' organisation & BSc/MSc structure
- ❖ Teaching strategy 'optimisation'

Theory & Practice Integration



Theory & Practice Integration

- ✓ Difficult task:
 - ‘Substrate’ quality
 - Previous basic course levels (instructor skills)
 - Lecture distribution: lecture rooms & labs facilities
 - Variable course topic development
- ✓ ‘Adaptive’ system
- ✓ Standard tools? Apps, GUI, ...
- ❖ Teaching methodology ‘optimisation’
- Matlab & Simulink

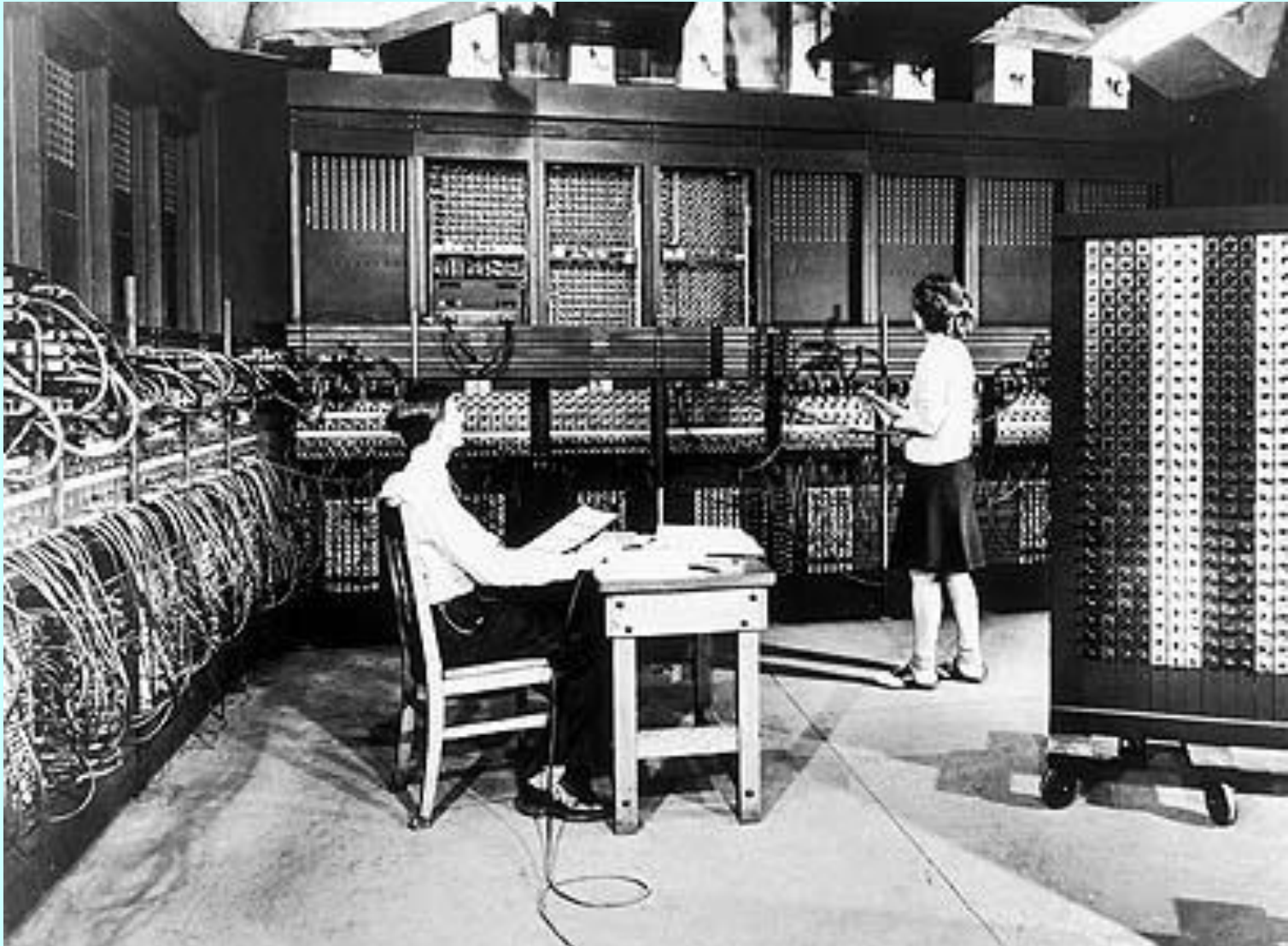
Engaging Students



Engaging Students

- ❖ Learning by doing
- ❖ Bridging theory & practice
- Tools: Matlab & Simulink basics
 - 2nd & 3rd years of BSc
- ✓ Automatic Control & Digital Control Systems
- ✓ 2016: Basic issues of Estimation Theory
- ❖ 'Adaptive' teaching strategy required
- Matlab & Simulink @ EnDiF

Numerical Tools



Numerical Tools

- ❖ 1993: Matlab @ Ferrara University
- ❖ 1999: Simulink
- Other numerical & programming codes
 - Pascal, Fortran, C...
- ✓ 2000: Matlab & Simulink used in Automatic Control courses & lecture notes
- ✓ – 2003: practice disconnected from theory
- ❖ ‘Adaptive’ teaching methodology development
- Examples with Matlab & Simulink

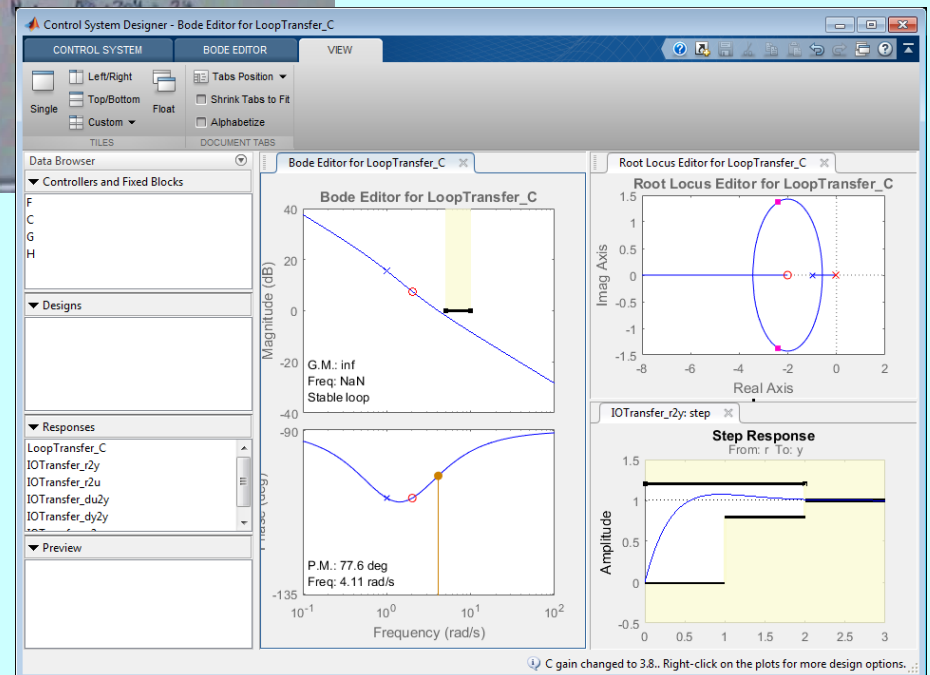
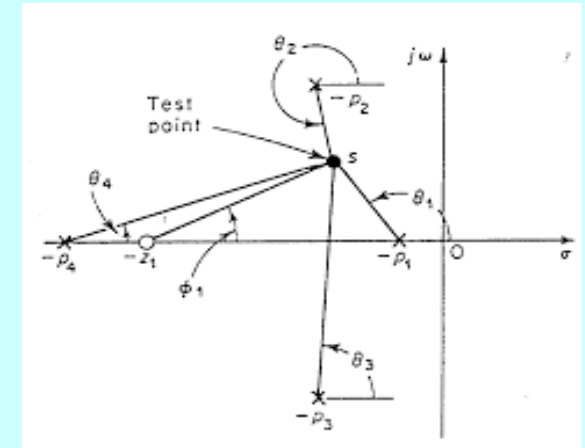
Lead Compensator Design in Root Locus

Handwritten notes on the whiteboard:

- $F(s) = \frac{1}{s(s+1)}$
- 15%
- 0.3 sec
- Root locus plot showing poles at $s=0$ and $s=-1$, and a zero at $s=-2$. The plot is drawn on a grid with σ (rad/s) on the horizontal axis and $j\omega$ (rad/s) on the vertical axis.
- Angles: 180° , 90° , 0° , 270° , 180° , 90° , 0° , 270°
- Gain: $K=10$
- Handwritten calculations:
 - $M_p = \exp\left(\frac{-\pi\zeta}{\sqrt{1-\zeta^2}}\right)$
 - $\zeta = 0.59 \Rightarrow 0.59 \text{ rad}$
 - $t_r = \frac{\pi - \phi}{\omega_d} = \frac{\pi - 59^\circ}{\omega_d} = 0.3 \text{ s}$
 - $\omega_d = 7 \text{ rad/s}$
 - $\sum \angle = 180^\circ (2k+1)$
 - $\angle \frac{1}{s} = -90^\circ$, $\angle \frac{1}{s+1} = -90^\circ$, $\angle \frac{1}{s+2} = -90^\circ$

Software interface (Bode Editor for Loop Transfer Function):

- CONTROL SYSTEM
- CONTROL SYSTEM
- Left/Right
- Top/Bottom
- Custom
- Single
- Float
- TILES
- DATA BROWSER
- Controllers and Fixed Blocks
- BODE EDITOR
- Tab Position
- Shrink Tabs to Fit
- Alphabetize
- DOCUMENT TABS
- Bode



Bridging Theory & Practice (1)

➤ Example: difference equations (Digital Control)

✓ Fibonacci equation

- From theory

$$F_n = \frac{(1 + \sqrt{5})^n - (1 - \sqrt{5})^n}{2^n(\sqrt{5})}$$

✓ To practice

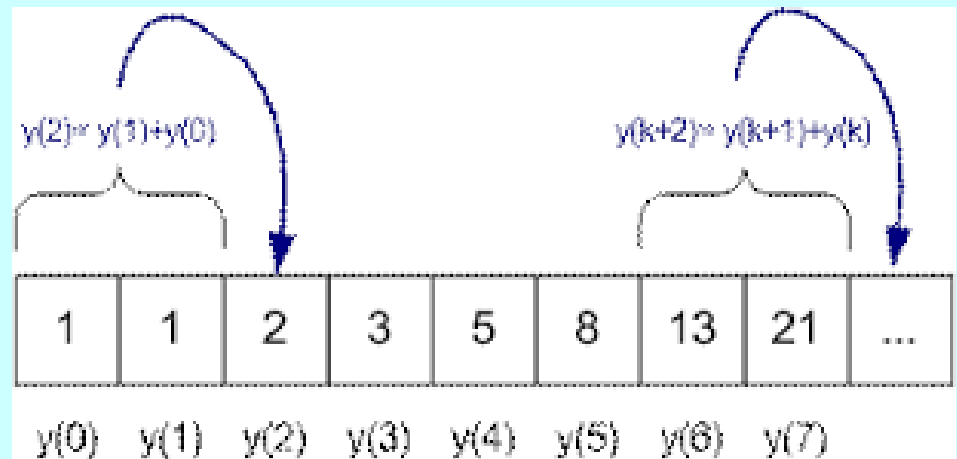
➤ Solution

➤ Stability concepts

➤ Matlab arrays

➤ Graphs

➤ Simulin blocks



Bridging Theory & Practice (2)

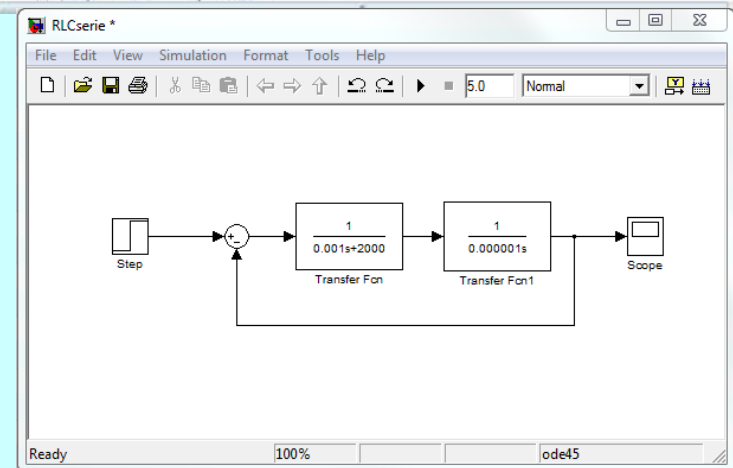
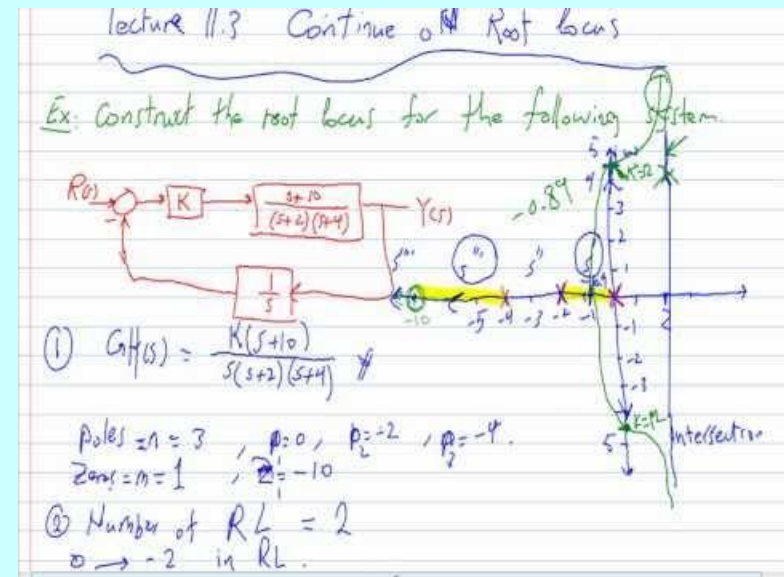
➤ Example: digital control system design

✓ Analytical approach

- From theory

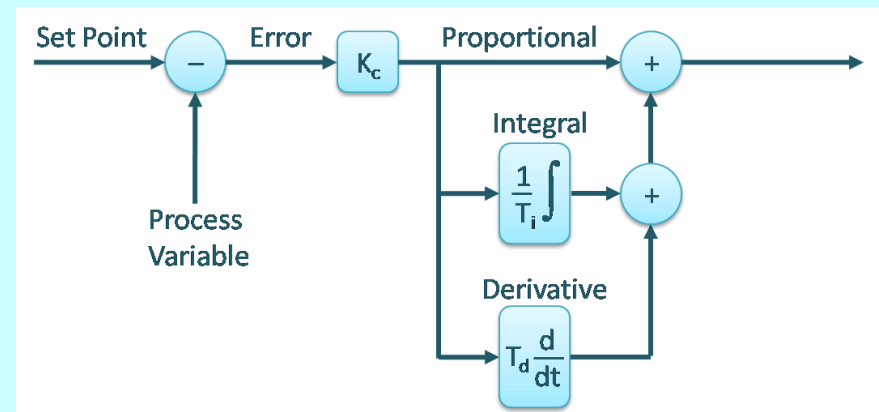
✓ To practice

- Transfer functions
- Root locus
- Lead & lag networks
- Simulink PID autotuning
- Advanced control...



Bridging Theory & Practice (3)

- Example: PID controllers
- ✓ Design approach
 - Z-N + oscillation method
- ✓ To practice
 - Critical gain
 - PID parameters
 - Autotuning with Simulink
 - Matlab code
 - Matlab functions

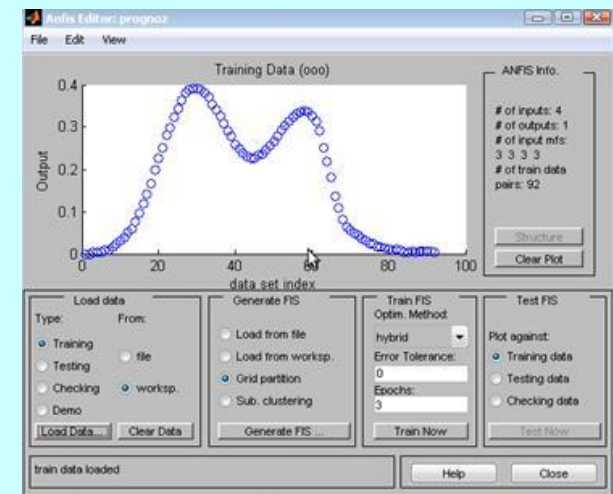
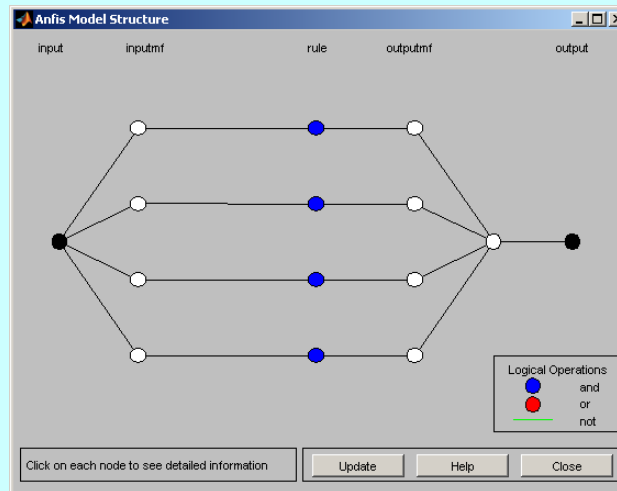
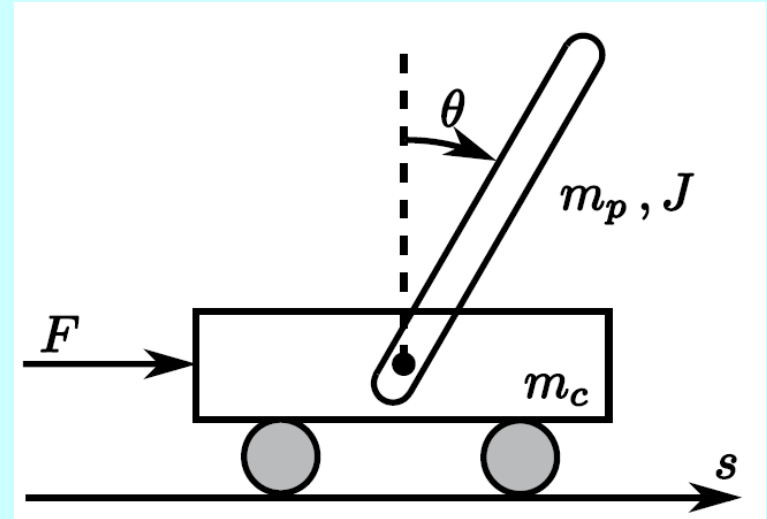


Controller	K_p	T_i	T_d
P	$0.5 K_{cr}$	Infinity	0
PI	$0.45 K_{cr}$	$P_{cr}/1.2$	0
PID	$0.6 K_{cr}$	$P_{cr}/2$	$0.125 P_{cr}$

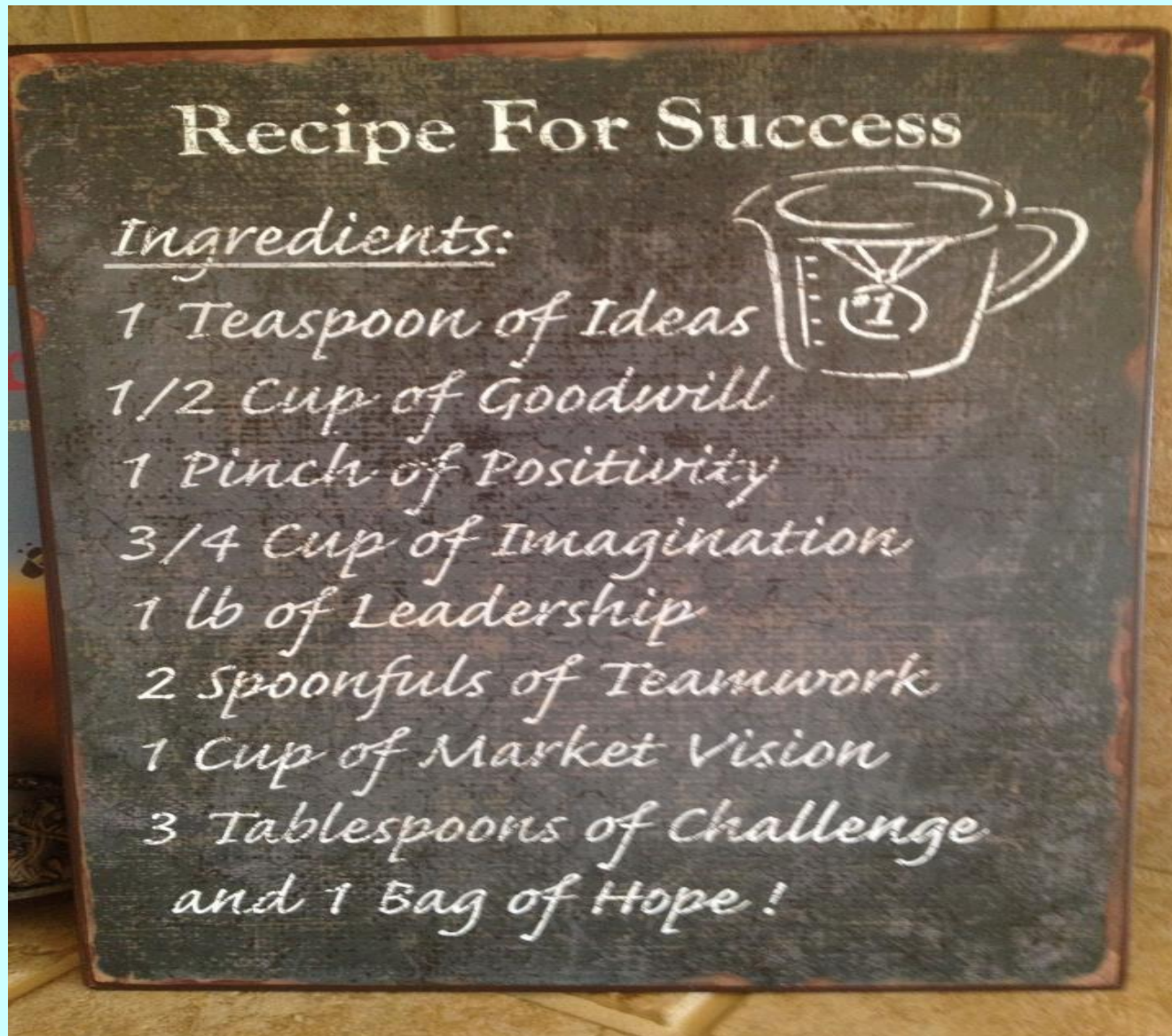
```
function [ output_args ] = Untitled( input_args )
%UNTITLED Summary of this function goes here
% Detailed explanation goes here
end
```

Bridging Theory & Practice (4)

- Example: nonlinear control
- ✓ Analytical approach
 - From theory (FL - SM)
- ✓ To practice
 - Neural networks
 - Fuzzy logic
 - ANFIS
 - nntool
 - LQR/LQG



A Recipe for Success?



Bridging Theory & Practice

➤ Tough task

❖ Complex trade-off

- ‘Substrate’ quality: varies every year
- Topic development: changing requirements

❑ Lecture topic synchronisation

❑ Advanced tool standardisation (e.g. Apps, GUI)

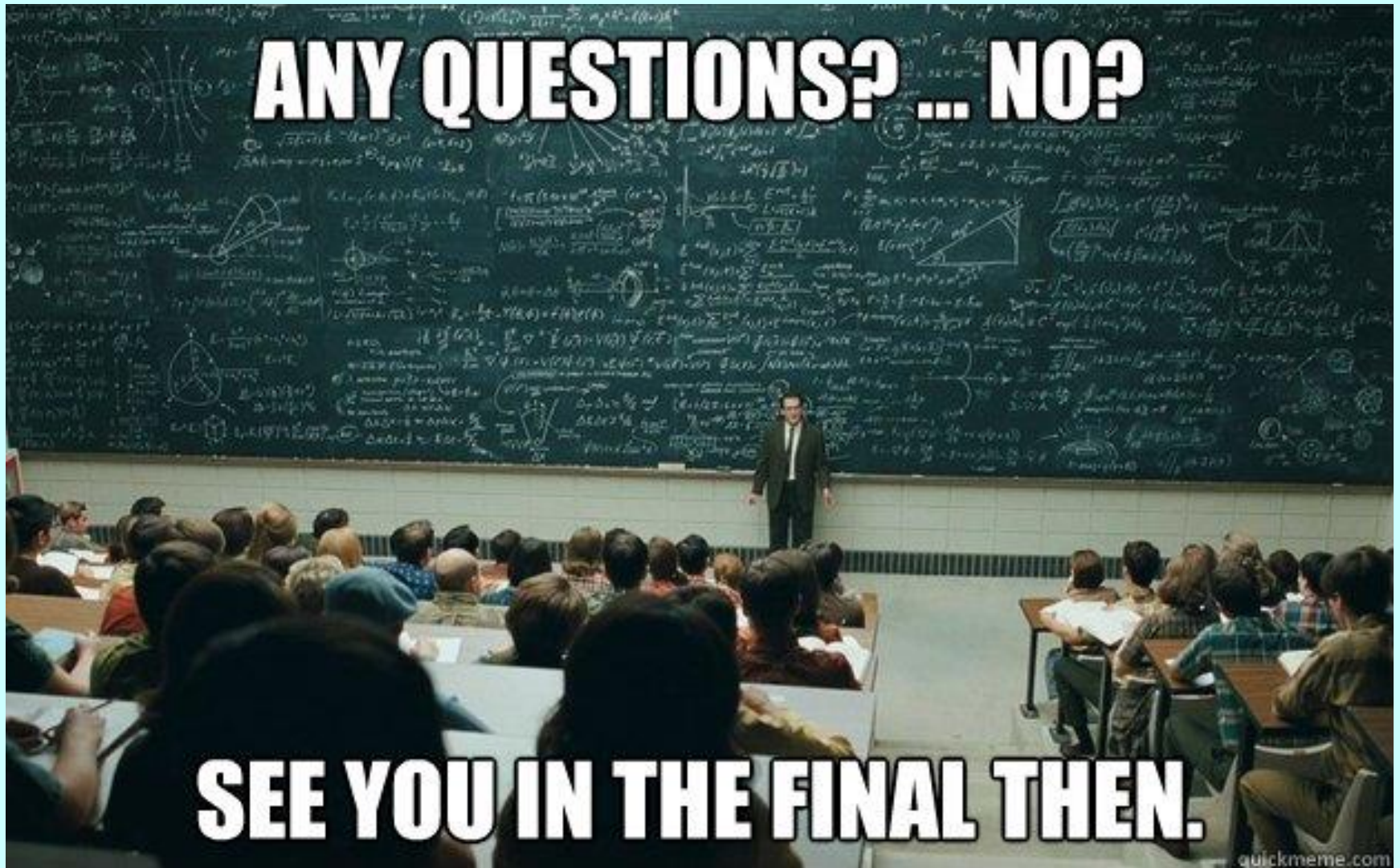
❖ It can be enhanced using basic tools

... Still working on it!

Concluding Remarks

- ✓ Theory & practice integration
- ✓ Matlab & Simulink tools
- ✓ Integrated in Control Engineering curriculum
- Interdisciplinary teaching enhanced
- Courses are connected with a common set of tools
- ❖ University-industry technology transfer
- ❖ Independent study essential for professional engineer

Thanks You for Listening



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